

Numerical Methods for Elliptic and Parabolic Partial Differential Equations

Sheet 5

Deadline: 27.10.17, 12:00.

Let $\mathcal{G} := \{\tau_i : 0 \leq i \leq n\}$ be a partition of $\Omega = [a, b]$, i.e. $\tau_i := [x_i, x_{i+1}]$ for some $a = x_0 < x_1 < \dots < x_{n+1} = b$. We define

$$S_{\mathcal{G}}^{1,0} := \{\varphi \in C^0([a, b]) \mid \forall \tau \in \mathcal{G} : \varphi|_{\tau} \in \mathbb{P}_1\} \cap H_0^1(\Omega) \\ = \text{span}\{b_i(x), 1 \leq i \leq n\},$$

where

$$b_i(x) := \begin{cases} \frac{x-x_{i-1}}{x_i-x_{i-1}} & x \in \tau_{i-1}, \\ \frac{x-x_{i+1}}{x_i-x_{i+1}} & x \in \tau_i, \\ 0 & \text{otherwise,} \end{cases}$$

are the piecewise linear “hat functions” on \mathcal{G} .

Exercise 1 (6 P.)

- (a) Implement a (MATLAB) program, which computes for a given partition \mathcal{G} and a given function $f : \Omega \rightarrow \mathbb{R} \in C^0(\Omega)$ the solution of the linear system $\mathbf{A}\mathbf{u} = \mathbf{r}$, where

$$\mathbf{A} = (a_{ij})_{i,j=1}^n, \quad a_{ij} := \int_0^1 b'_i \cdot b'_j + \int_0^1 b_i \cdot b_j \quad \text{and} \quad \mathbf{r} = (r_i)_{i=1}^n, \quad r_i := \int_0^1 f \cdot b_i.$$

Find an explicit formula for the entries of \mathbf{A} . You can use the MATLAB function `integral` to compute the vector \mathbf{r} .

- (b) Use your program to determine approximated solutions of the boundary value problem

$$-u''(x) + u(x) = 1 \quad \text{in } \Omega = (0, 1), \quad u(0) = u(1) = 0. \quad (\text{BVP})$$

Plot the exact solution of the problem (BVP) and the approximated solutions for different partitions of \mathcal{G} .

Exercise 2 (6 P.)

We set $\Omega = [0, 1]$. Let \mathcal{G} a partition of $\bar{\Omega}$ and $\tilde{\mathcal{G}}$ a refinement of \mathcal{G} .

- (a) Write a (MATLAB) program, that refines a given subdivision \mathcal{G} by interval halving. The output is the resulting subdivision $\tilde{\mathcal{G}}$.
- (b) Write a (Matlab-)program, that calculates for the given coefficient vectors $\mathbf{u}, \mathbf{v} \in \mathbb{R}^n$ the $H^1(\Omega)$ -norm of the difference of the corresponding functions $u := \sum_{i=1}^n \mathbf{u}_i b_i \in S_{\mathcal{G}}^{1,0}$ and $v := \sum_{i=1}^n \mathbf{v}_i b_i \in S_{\tilde{\mathcal{G}}}^{1,0}$.

Hint: Use the matrix \mathbf{A} from Exercise 1.

- (c) Write a (Matlab-)program, that calculates for a given coefficient vector \mathbf{u} of a function $u \in S_{\mathcal{G}}^{1,0}$ the coefficient vector of \mathbf{u} with respect to the refined mesh $\tilde{\mathcal{G}}$ and the space $S_{\tilde{\mathcal{G}}}^{1,0}$ respectively.
- (d) Write a (Matlab-)programm, that estimates the error of the finite-element-approximation $u \in S_{\mathcal{G}}^{1,0}$ from Exercise 1 in the $H^1(\Omega)$ -norm. To do this, choose a suitable refinement $\tilde{\mathcal{G}}$ of the partition \mathcal{G} (see (a)), determine the coefficients of u with respect to $\tilde{\mathcal{G}}$ (see (c)) and compare them with the finite-element-approximation with respect to the subdivision $\tilde{\mathcal{G}}$ (see (b)).

Exercise 3 (3. P.)

Consider the following partial differential equation for $f \in C^0([0, 1])$:

$$u''(x) = f(x) \quad \text{in } \Omega = (0, 1), \quad u'(0) = u'(1) = 0. \quad (1)$$

- (a) Explain why this equation is not well posed in $H^1(\Omega)$.
- (b) Let $f(x) = (x - 1/2)$ and add the additional boundary condition $u(0) = 0$ to the PDE. What basis for a finite dimensional subspace $S \subset S_{\mathcal{G}}^1 := \{\varphi \in C^0([0, 1]) \mid \forall \tau \in \mathcal{G} : \varphi|_{\tau} \in \mathbb{P}_1\}$ do you choose to approximate the solution u numerically ?